Robots learning about objects from the Web

June 21, 2017

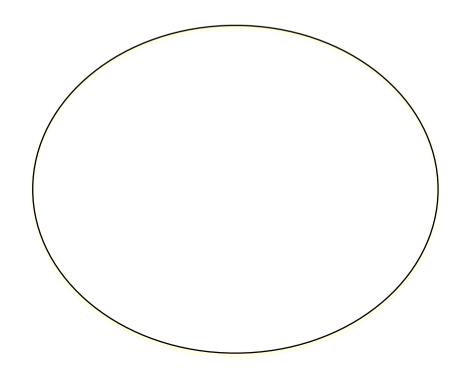
Barbara Caputo

Visual And Multimodal Applied Learning (VANDAL) Laboratory Department of Computer, Control and Management Engineering



Suppose you have a robot at home...

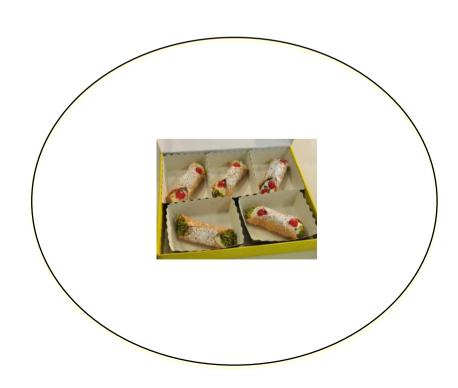




Suppose you have a robot at home...

What is this on the table??

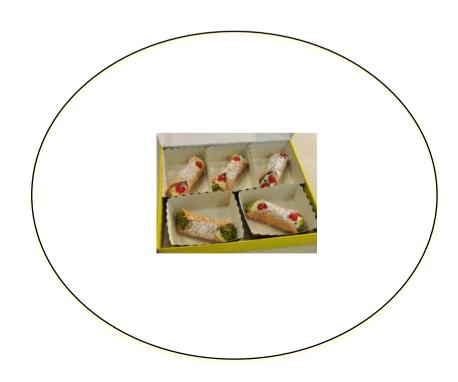




Option A: asking a human

What is this on the table?? Let me ask Barbara...





Option A: asking a human

- > Robots learn from own experience guided by humans
 - > Human-robot interaction [Kjellstrom et al 2011,Billard&Grollman 2013]
 - > Learning by demonstration [Argall et al 2009]





Option B: learning by itself

What is this on the table??
Let me try to figure it out

. .





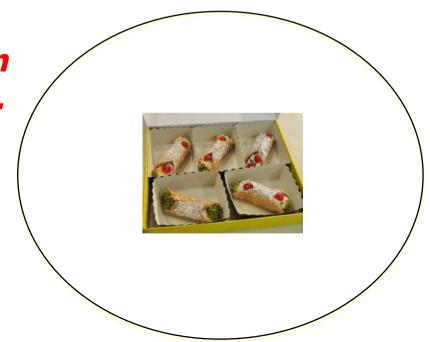
Option B: learning by itself

- > Robots learn from own experience alone
 - > Developmental robotics [Asada et al 2009, Tsai & Kujpers 2013, 2014...]



What is this on the table??
Let me take a snapshot
and search on the Web...

...if the robot could learn from the Web like us....





Let's see on the Web..



Editor: Kate Hollinger

Copyright, 2009, Maria Liberati

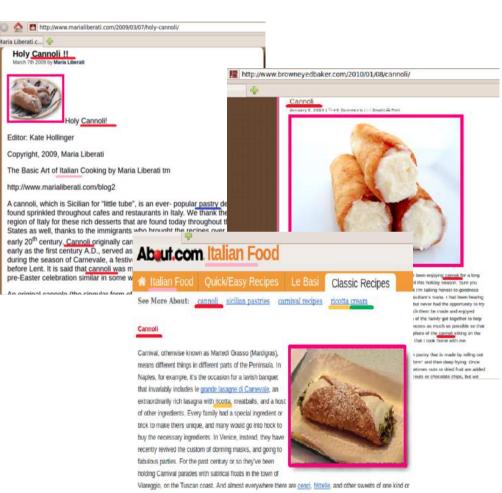
The Basic Art of Italian Cooking by Maria Liberati tm

http://www.marialiberati.com/blog2

A cannoli, which is Sicilian for "little tube", is an ever-popular pastry dessert found sprinkled throughout cafes and restaurants in Italy. We thank the Siciliar region of Italy for these rich desserts that are found today throughout the Unite States as well, thanks to the immigrants who brought the recipes over in the early 20th century. Cannoli originally came from the Palermo region of Sicily as early as the first century A.D., served as a treat and given to friends in dozens during the season of Carnevale, a festive European celebration held right before Lent. It is said that cannoli was most likely a symbol of fertility during the pre-Easter celebration similar in some ways to Mardi Gras.



Let's see on the Web..



Viareggio, on the Tuscan coast. And almost everywhere there are cend, frittelle, and other sweets of one kind or another to liven the merrymaking. Among the most glorious are Cannolli, Palermo's fried waters filled with an airy mixture of ricotta, candled fruit, chocolate, and other ingredients, which are so tasty that they have spread not just throughout the island, but to wherever Sicilians have settled, and are now greeted with joy year round.

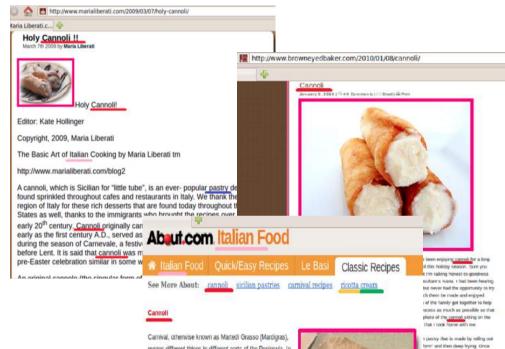
In the past, when they were "Carnival's Crown," according to Giuseppe Pitre (the doctor and ethnographer who founded Patermo's museum of folk culture in 1909), people gave cannoil to all their friends – by the dozen. One can only imagine the people in the pastry shops churning them out and the sweet sugary smell of the notata filling walting over the cityl They are older, however: Pitrè also quotes an anonymous 17th century poet, who said:



Let's see on the Web..



...cannoli..pastry.. ricotta filled.. goes in the fridge..



means different things in different parts of the Peninsula. In Naples, for example, it's the occasion for a lavish banquet. that invariably includes le grande lasagne di Camevale, an extraordinarily rich lasagna with ricotta, meatballs, and a host of other ingredients. Every family had a special ingredient or trick to make theirs unique, and many would go into hock to buy the necessary ingredients. In Venice, instead, they have recently revived the custom of donning masks, and going to fabulous parties. For the past century or so they've been holding Carnival parades with satirical floats in the town of

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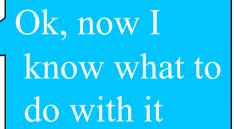
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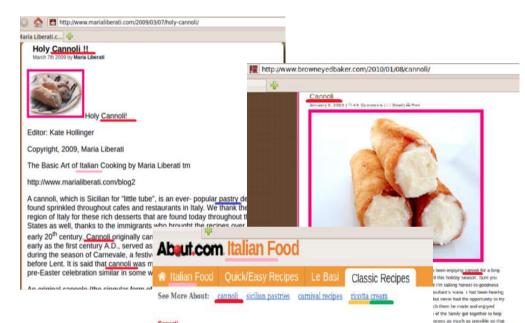


Let's see on the Web...



..cannoli..pastry..
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Cannoli

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photo of the cannoli sitting on the that I took home with me.

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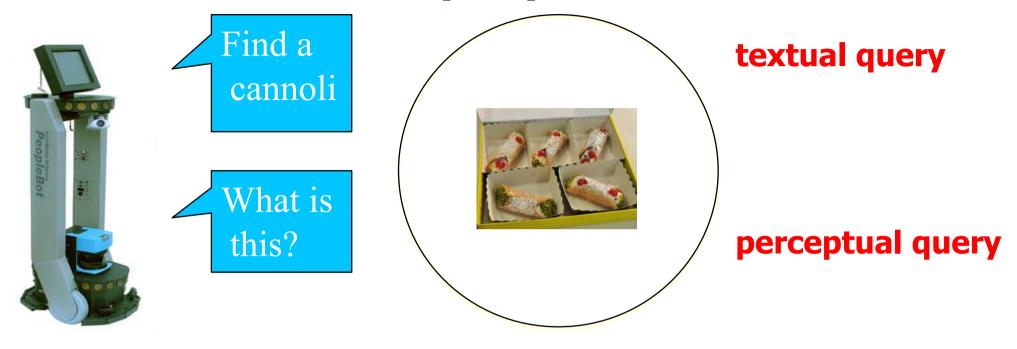
To make this work, we have several challenges, such as:

- 1. How to extract from the Web information useful for a robot, from a robot query?
- 2. How to make such information usable by robots?
- 3. How to update continuously the perceptual and semantic Web -created knowledge bases?
- 4.

Focus on perceptual knowledge (images, depth); Visual learning tool of choice: deep learning

How to find usable perceptual knowledge on the Web?

How would a robot query the web?



Rather than mining the Web on the fly, we might build clean Web-proxies, large enough to cover for most (any?) query

...but isn't this ImageNet????



(Some) Open Issues

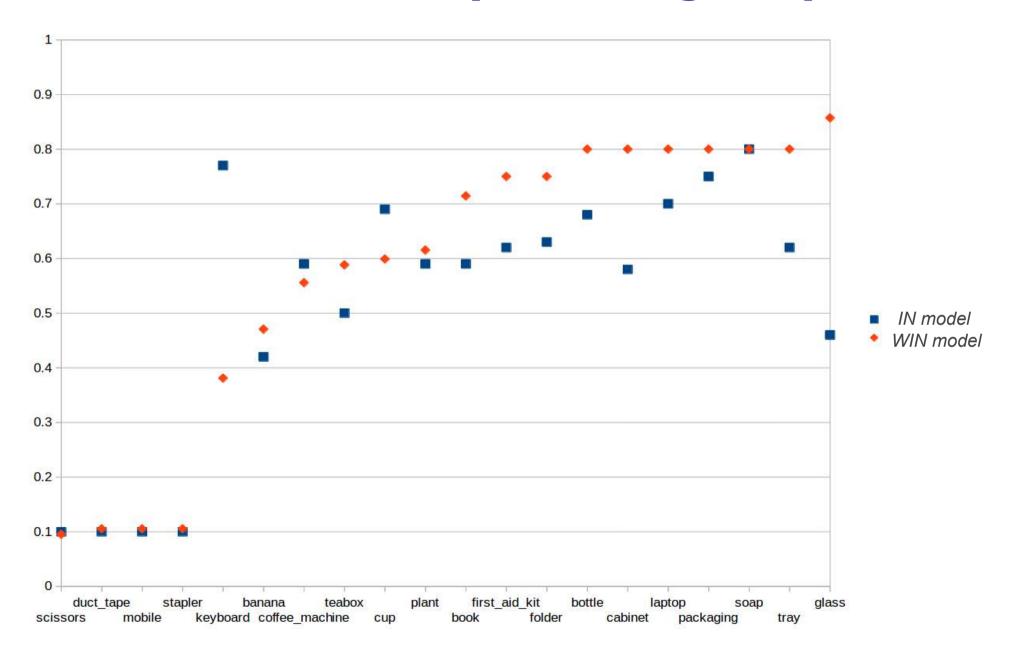
ImageNet is a db created in 2012 of 1K categories —**static, closed** world assumption

- 1. What if we could continuously update all its classes?
- 2. What if we could augment its classes (1k, 3K, ..10K)?
- 3. What if we could exploit prior knowledge on the task and build on demand task specific databases?

Can we automatically generate larger/task specific databases?

Proof of concept: generate a copy of ImageNet by downloading images using the class names as queries

Results with AlexNet(Web-ImageNet)



(Some) Open Issues

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Issues to deal with:

- 1. How to minimize noisily annotated images when harvesting the Web
- 2. What is the effect of noise on a given CNN architecture

Harvesting the Web –SEO Keywords

- We take advantage of the Search Engine Optimization (SEO) practice of keyword research.
- > SEO professionals research keywords, which they use to achieve better rankings in search engines.

Tool of choice: MyKeyWorder

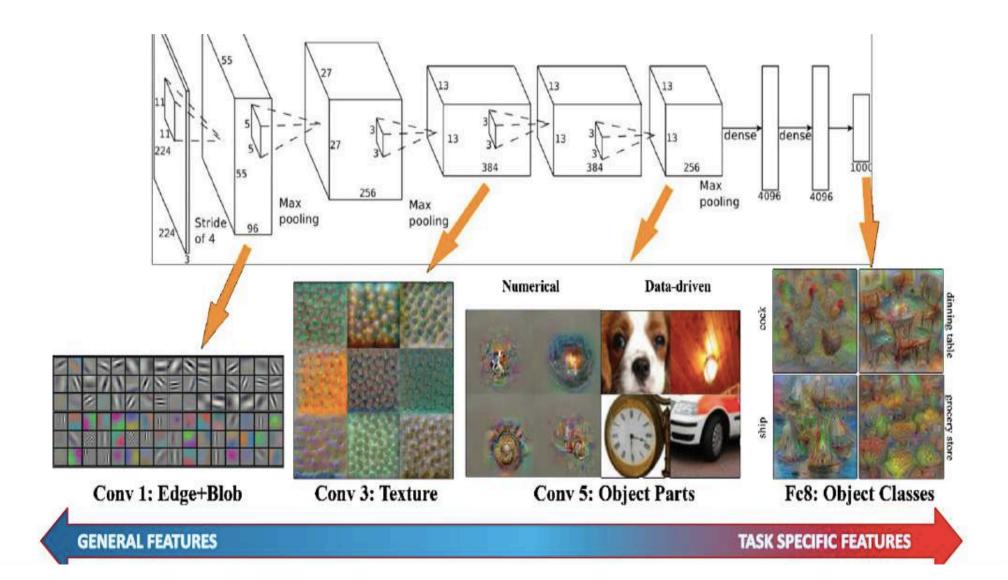
- > It references language content from Princeton's Wordnet and Moby Thesaurus.
- It takes a query and returns lists of keywords associated with it, sorting them by relevance and frequency.

Harvesting the Web –SEO Keywords



Icecream - WINC

How does noise affects CNNs?



How does noise affects CNNs?

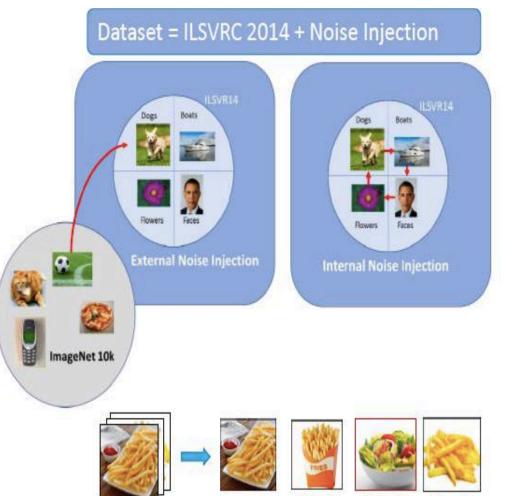
Original dataset	ILSVRC 2014 classification
Object Categories	1000
Number of images	1,281167 (700-1300 images per cat.)

DATASET

- 2 types of Noise Injection: Internal and External
- 9 percentages of Noise Injection: 5% 15% 25% ... 75% 85%

TRAINING

- 2 different architectures: AlexNet , GoogleNet
- Training details
 - o 60 Epochs
 - Stochastic Gradient descrent
 - Learning rate 0.01
 - Learning rate update: step
 - o Momentum 0.9



Fries 1

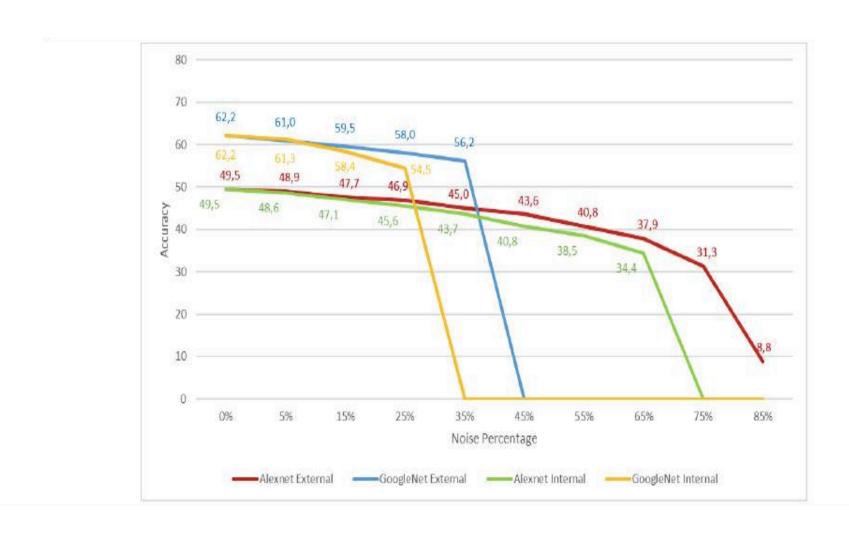
Label: French Fries

Fries 2

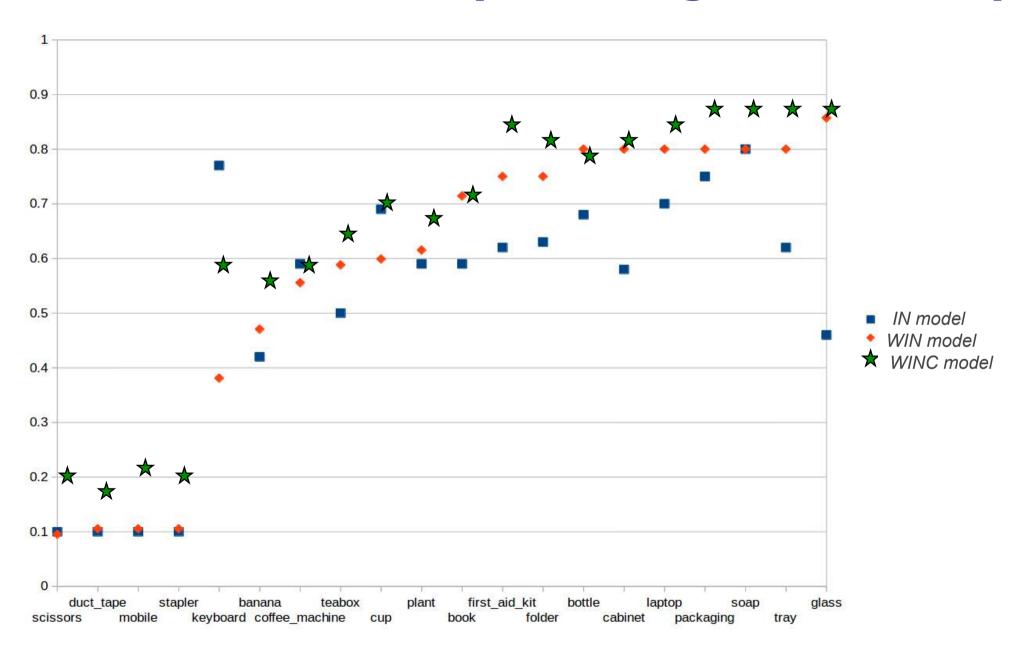
Fries 4

Fries 3

How does noise affects CNNs?



Results with AlexNet(Web-ImageNet-Cleaned)



Putting all the pieces together

- 1. We generate WINC (Web-ImageNet-Cleaned) and train a GoogLeNet on it
- 2. We use this CNN to make predictions on Bob and Betty
- 3. We further use semantic context as a heuristic to indicate our preferences from the CNN list of predictions
- 4. From this preferred subset we rank by the CNN's confidence and pick the highest

[Massouh, Babiloni, Tommasi, Young, Hawes and Caputo, IROS 2017] [Young, Basile, Cabrio, Caputo, Kunze and Hawes, ICRA 2017]





Context 1. Coffee 2. Toaster 3. Oven 4. Plate 5. Pyrex

Context

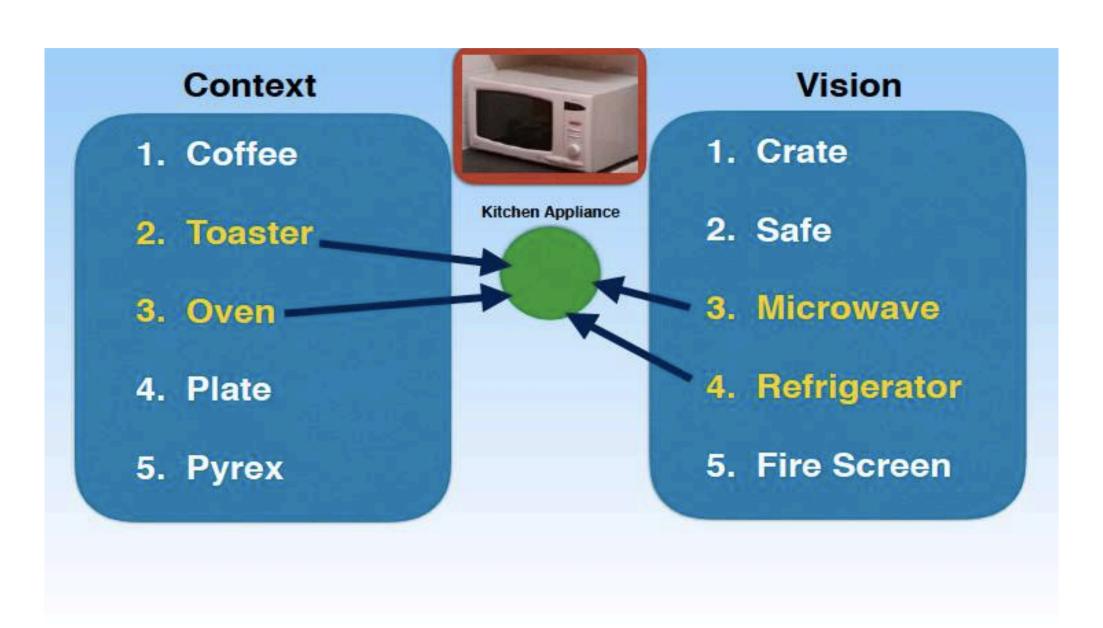
- 1. Coffee
- 2. Toaster
- 3. Oven
- 4. Plate
- 5. Pyrex

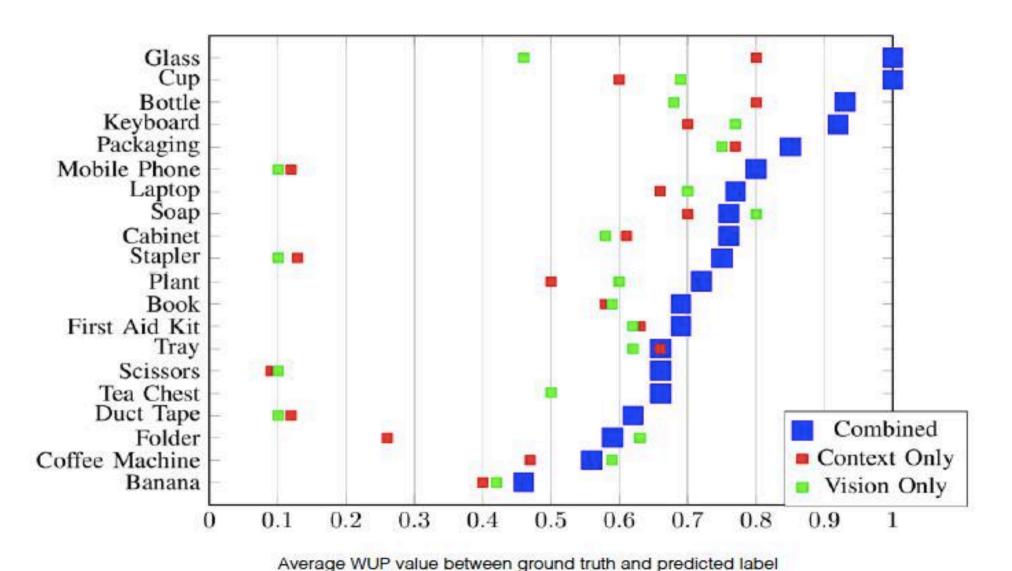


Vision

- 1. Crate
- 2. Safe
- 3. Microwave
- 4. Refrigerator
- 5. Fire Screen

Context Vision 1. Crate 1. Coffee 2. Safe 2. Toaster 3. Microwave 3. Oven 4. Refrigerator 4. Plate 5. Fire Screen 5. Pyrex





Learning about objects from the Web Q:

1. How to find usable perceptual knowledge from the Web?



A:

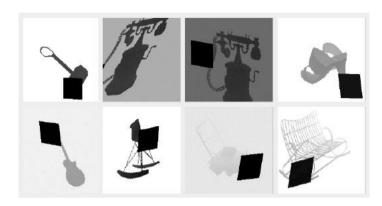
1. Build automatically Web-based perceptual knowledge bases, generic and task specific

Moving forward

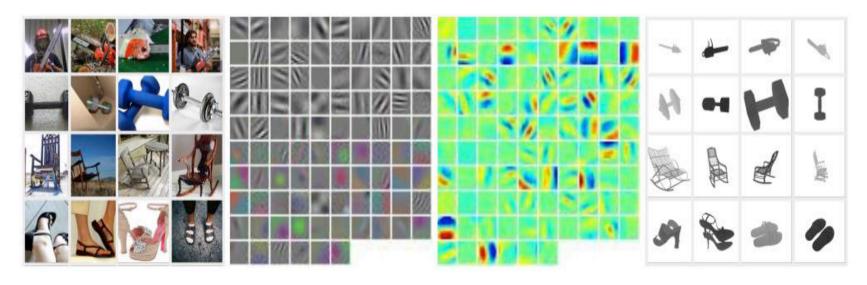
Harvesting 3D percepts from the Web

From 3D CAD models to synthetic depth → the VANDAL database

- ¥ 4.1 millions depth views
- 9.383 different CAD models (counting morphs)
- 319 object classes (ILSVRC 2014 subset)



Sample renderings with data augmentation



Imagenet samples

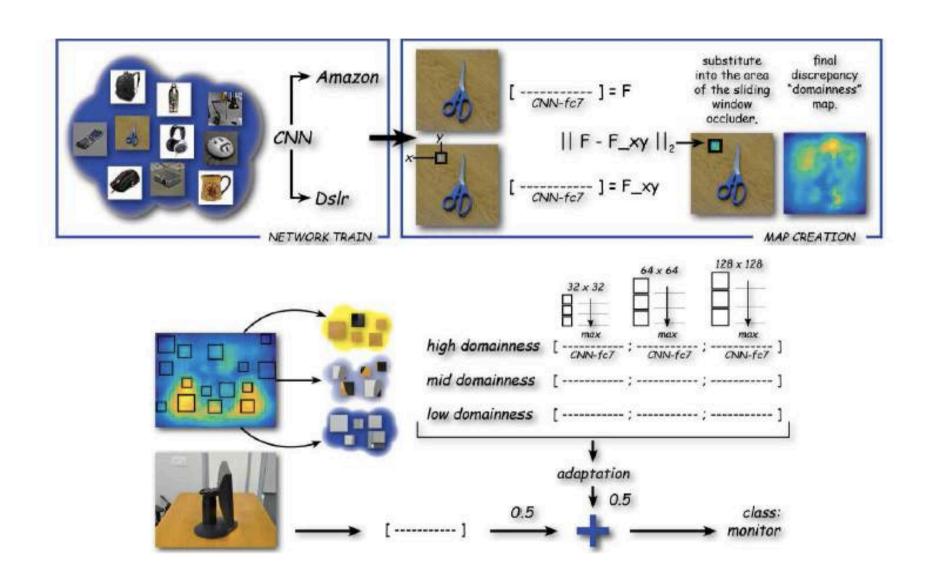
Imagenet filters

DepthNet samples

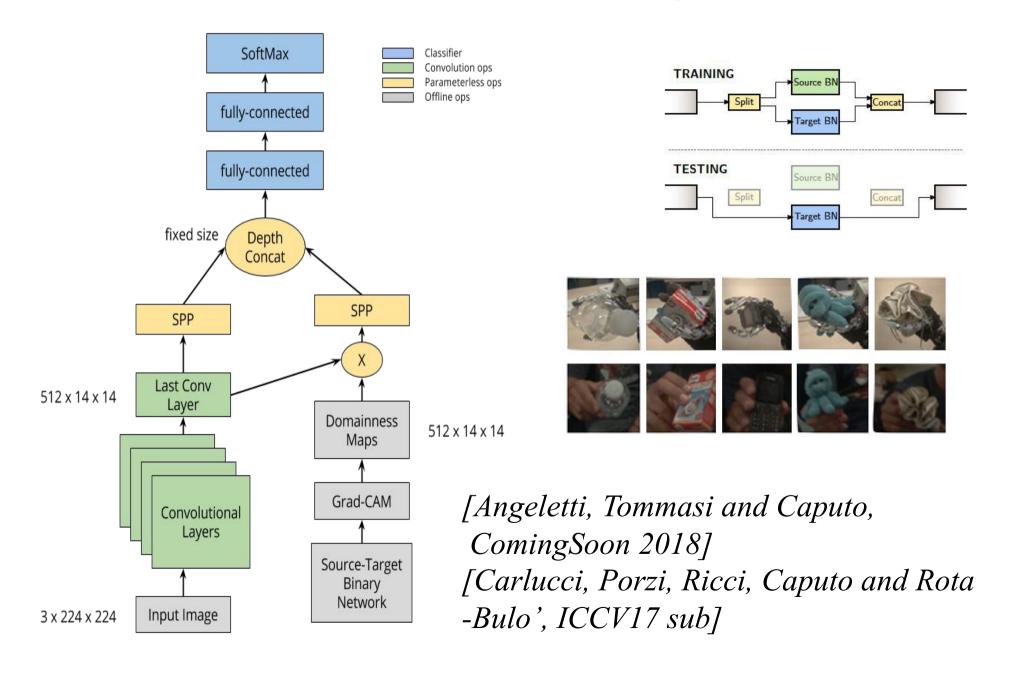
Vandal samples

[Carlucci, Russo and Caputo, ICRA 2017]

Can we localize the domain shift?

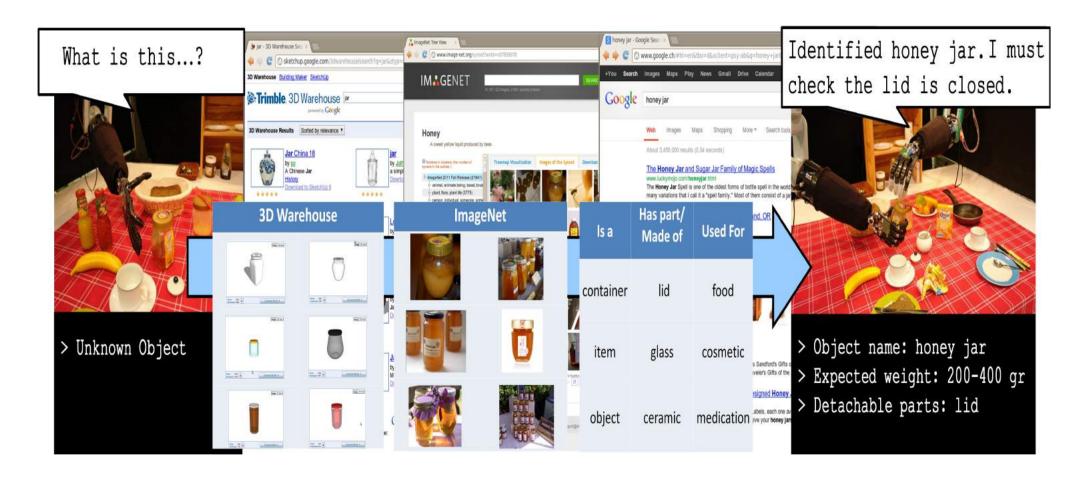


Can we embed domainness maps in a CNN?



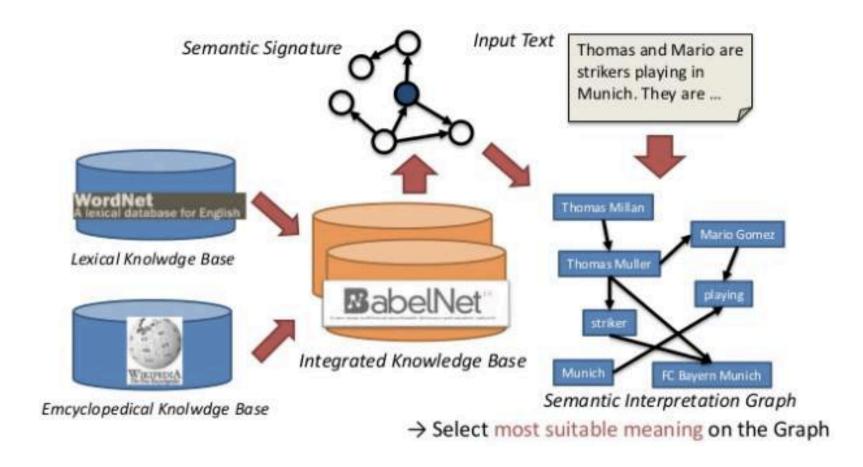
Learning about objects from the Web: where does manipulation fit in?

An object is far more than its name...



Leveraging over 3D and 2D perceptual data freely available from the Web, linking it to structured semantic knowledge about objects

An object is far more than its name...



Leveraging over 3D and 2D perceptual data freely available from the Web, linking it to structured semantic knowledge about objects

A final though



A final though



- Embodied cognition has been the leading principle in artificial cognitive system research over the last 10 years
- > **BUT** we humans learn also from externalized knowledge —like books, the Web, virtual reality....



..this is what this is about!



Thanks for your attention



